

Problem 1.

Answer (4).

$$\begin{aligned} \therefore \text{Transfer function } H(s) &= \frac{\frac{1}{T_1 s + 1} \cdot \frac{1}{T_2 s + 1} \cdot \frac{1}{T_3 s + 1}}{1 + \frac{1}{T_1 s + 1} \cdot \frac{1}{T_2 s + 1} \cdot \frac{1}{T_3 s + 1}} \\ &= \frac{1}{(T_1 s + 1)(T_2 s + 1)(T_3 s + 1) + 1} \end{aligned}$$

Characteristic function:

$$1 + (T_1 s + 1)(T_2 s + 1)(T_3 s + 1) = 0$$

$$T_1 T_2 T_3 s^3 + (T_1 T_2 + T_1 T_3 + T_2 T_3) s^2 + (T_1 + T_2 + T_3) s + 2 = 0$$

$$T_1, T_2, T_3 \neq 0$$

$$\therefore s^3 + \left(\frac{1}{T_1} + \frac{1}{T_2} + \frac{1}{T_3}\right) s^2 + \left(\frac{1}{T_1 T_2} + \frac{1}{T_2 T_3} + \frac{1}{T_1 T_3}\right) s + \frac{2}{T_1 T_2 T_3} = 0$$

Routh's table:

$$\begin{array}{l} s^3 \quad 1 \quad \frac{1}{T_1 T_2} + \frac{1}{T_2 T_3} + \frac{1}{T_1 T_3} \\ s^2 \quad \frac{1}{T_1} + \frac{1}{T_2} + \frac{1}{T_3} \quad \frac{2}{T_1 T_2 T_3} \\ s^1 \quad \frac{\left(\frac{1}{T_1} + \frac{1}{T_2} + \frac{1}{T_3}\right) \left(\frac{1}{T_1 T_2} + \frac{1}{T_2 T_3} + \frac{1}{T_1 T_3}\right) - \frac{2}{T_1 T_2 T_3}}{\frac{1}{T_1} + \frac{1}{T_2} + \frac{1}{T_3}} \quad 0 \\ s^0 \quad \frac{2}{T_1 T_2 T_3} \end{array}$$

\therefore if system is stable, then the first column should be positive, which is decided by T_1, T_2, T_3 .

\therefore Correct answer is (4).

Problem 2:

1). System transfer function: $H(s) = \frac{AG(s)}{1+AG(s)}$

$$H(s) = \frac{\frac{A}{K}}{\left(\frac{s}{\omega_n}\right)^2 + 2\zeta \frac{s}{\omega_n} + 1 + \frac{A}{K}} = \frac{\frac{A}{K} \omega_n^2}{s^2 + 2\zeta \omega_n s + \omega_n^2 \left(1 + \frac{A}{K}\right)}$$

$$= \frac{\frac{A}{K} \omega_n^2 \sqrt{\left(1 + \frac{A}{K} - \zeta^2\right)}}{\left(s + \zeta \omega_n\right)^2 + \omega_n^2 \cdot \left(1 + \frac{A}{K} - \zeta^2\right)} \cdot \frac{1}{\sqrt{1 + \frac{A}{K} - \zeta^2}}$$

$$\therefore \mathcal{L}^{-1}(e^{-at} \sin \omega t) = \frac{\omega}{(s+a)^2 + \omega^2}$$

$$Y(t) = \delta(t) \quad \therefore R(s) = 1$$

$$Y(s) = H(s) \cdot R(s) = H(s)$$

$$\therefore y(t) = \frac{\frac{A}{K} \omega_n}{\sqrt{1 + \frac{A}{K} - \zeta^2}} e^{-\zeta \omega_n t} \sin\left(\omega_n \sqrt{1 + \frac{A}{K} - \zeta^2} t\right)$$

\therefore frequency of oscillation of the output $y(t)$ will change when A changes.

2). A will affect frequency of oscillation of the output,
 A will also affect the magnitude.

However A won't affect the term $e^{-\zeta \omega_n t}$

\therefore A won't change the time required for the oscillatory impulse response to decay away.

Problem 3.

$$G(s) = \frac{1}{s(s+3)}, \quad G_c(s) = \frac{ks}{s+p}$$

transfer function $H(s) = \frac{G(s)G_c(s)}{1 + G(s)G_c(s)} = \frac{ks}{s(s+3)(s+p) + ks}$

$$H(s) = \frac{k}{(s+3)(s+p)+k} = \frac{k}{s^2 + (3+p)s + 3p+k}$$

$$\begin{cases} 2\zeta\omega_n = 3+p \\ \omega_n^2 = 3p+k \end{cases}$$

$$M_p = 5\%, \quad t_s = \frac{3}{4} \text{ s.}$$

\therefore settling time for 5% criterion is $\frac{3}{\sigma}$

$$\therefore \frac{3}{\sigma} = \frac{3}{4} \quad \sigma = 4$$

$$\therefore \zeta\omega_n = \sigma \quad \therefore \zeta\omega_n = 4$$

From M_p versus ζ for the second-order system figure, we know

$$M_p = 5\% \Rightarrow \zeta = 0.7$$

$$\therefore \zeta\omega_n = 0.7\omega_n = 4 \quad \therefore \omega_n = \frac{40}{7}$$

$$\therefore 2\zeta\omega_n = 3+p = 8 \quad \therefore p = 5$$

$$3p+k = \omega_n^2 = \frac{1600}{49} = 15+k$$

$$\therefore k = \frac{1600}{49} - 15 = \frac{865}{49}$$

Problem 4.

System is: $\frac{as+b}{s^4+as^3+bs^2+cs+d}$

Proof:

the characteristic equation is:

$$s^4+as^3+bs^2+cs+d=0$$

Routh's table:

s^4	1	b	d
s^3	a	c	
s^2	$\frac{ab-c}{a}$	d	
s^1	$\frac{abc-c^2-ad}{a}$		
s^0	$\frac{ab-c}{a}$		
	d		

\therefore a, b, c, d are positive and $abc-c^2-a^2d > 0$

$$\therefore abc-c^2 > a^2d > 0$$

$$\therefore (ab-c)c > 0 \Rightarrow ab-c > 0$$

$$\therefore \frac{\frac{abc-c^2}{a} - ad}{\frac{ab-c}{a}} > 0$$

all the numbers in the first column are positive

\therefore System is stable.

EOP

Problem 5.

(1) From figure, we know, open-loop transfer function is:

$$KG(s) = \frac{25 \left(\frac{s}{10} + 1\right)^4}{s(s+1) \left(\frac{s}{1000} + 1\right)^3}$$

$$28 = 20 \log k \quad \Rightarrow \quad k = 25$$

(2) closed-loop transfer function: (Unity feedback)

$$H(s) = \frac{KG(s)}{1 + KG(s)}$$

$$\therefore Y(s) = H(s) \cdot R(s)$$

$$E(s) = R(s) - Y(s) = \frac{1}{1 + KG(s)} R(s) = \frac{s(s+1) \left(\frac{s}{1000} + 1\right)^3}{s(s+1) \left(\frac{s}{1000} + 1\right)^3 + 25 \left(\frac{s}{10} + 1\right)^4} R$$

$$e_{ss} = \lim_{s \rightarrow 0} sE(s) = \lim_{s \rightarrow 0} s \cdot \frac{s(s+1) \left(\frac{s}{1000} + 1\right)^3}{s(s+1) \left(\frac{s}{1000} + 1\right)^3 + 25 \left(\frac{s}{10} + 1\right)^4} \cdot \frac{1}{s^{k+1}}$$

$$k=0 \quad e_{ss} = 0$$

$$k=1 \quad e_{ss} = \frac{1}{25} = \frac{1}{k_v}$$

\therefore System type is 1, error constant $k_v = 25$.

Problem 6.

$$G(s) = \frac{2as + a^2}{s^2}$$

transfer function of close-loop: $H(s) = \frac{G(s)}{1+G(s)}$

$$Y(s) = H(s)R(s) = \frac{G(s)}{1+G(s)} R(s)$$

$$E(s) = R(s) - Y(s) = \frac{1}{1+G(s)} R(s)$$

for unit-step input: $R(s) = \frac{1}{s}$

$$\therefore E(s) = \frac{1}{1 + \frac{2as+a^2}{s^2}} \cdot \frac{1}{s} = \frac{s}{s^2 + 2as + a^2} = \frac{s}{(s+a)^2}$$

$$\therefore e(t) = (1-at)e^{-at}$$

$$e^2(t) = (1-at)^2 e^{-2at} = e^{-2at} - 2at e^{-2at} + a^2 t^2 e^{-2at}$$

$$\mathcal{L}(e^{-2at}) = \frac{1}{s+2a}$$

$$\mathcal{L}(-2at e^{-2at}) = -2a \cdot \frac{1}{(s+2a)^2}$$

$$\mathcal{L}(a^2 t^2 e^{-2at}) = 2a^2 \cdot \frac{1}{(s+2a)^3}$$

$$\therefore \mathcal{L}(e^2(t)) = \frac{1}{s+2a} - \frac{2a}{(s+2a)^2} + \frac{2a^2}{(s+2a)^3}$$

$$J_1 = \int_0^{+\infty} e^2(t) dt = \lim_{t \rightarrow \infty} \int_0^t e^2(t) dt = \lim_{s \rightarrow 0} s \cdot \frac{\mathcal{L}(e^2(t))}{s} = \lim_{s \rightarrow 0} \mathcal{L}(e^2(t))$$

$$= \lim_{s \rightarrow 0} \left[\frac{1}{s+2a} - \frac{2a}{(s+2a)^2} + \frac{2a^2}{(s+2a)^3} \right]$$

$$= \frac{1}{2a} - \frac{2a}{4a^2} + \frac{2a^2}{8a^3}$$

$$= \frac{1}{4a}$$

$$J_2 = \int_0^{+\infty} t e^{2t} dt$$

$$= \lim_{s \rightarrow 0} \int_0^t t e^{2t} dt = \lim_{s \rightarrow 0} s \cdot \frac{\mathcal{L}(e^{2t} \cdot t)}{s} = \lim_{s \rightarrow 0} s \frac{\mathcal{L}(e^{2t} \cdot t)}{s}$$

$$= \lim_{s \rightarrow 0} \mathcal{L}(te^{2t})$$

$$\mathcal{L}(te^{2t}) = - \frac{d \mathcal{L}(e^{2t})}{ds}$$

$$= - \left(- \frac{1}{(s+2a)^2} + \frac{4a}{(s+2a)^3} - \frac{6a^2}{(s+2a)^4} \right)$$

$$J_2 = - \lim_{s \rightarrow 0} \left(- \frac{1}{(s+2a)^2} + \frac{4a}{(s+2a)^3} - \frac{6a^2}{(s+2a)^4} \right)$$

$$= - \left(- \frac{1}{4a^2} + \frac{4a}{8a^3} - \frac{6a^2}{16a^4} \right)$$

$$= - \left(- \frac{1}{4a^2} + \frac{1}{2a^2} - \frac{3}{8a^2} \right)$$

$$= + \frac{1}{8a^2}$$